

## Lecture 8

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Today we will complete the description of Berlekump's deterministic algorithm for efficiently factorizing polynomials over  $\mathbb{F}_q$  (where  $q = p^t$  for a prime  $p$ ) in time polynomial in  $\deg(f)$ ,  $t$ ,  $p$ .

We will then begin laying the groundwork for algorithms that factor polynomials over  $\mathbb{Z}[x]$  and for factoring bivariate polynomials. We will see these two problems are related and introduce Hensel's Lifting, a useful tool for solving them.

## 1 A deterministic Algorithm—Continued

Recall that we saw in the last lecture that for any reducible polynomial  $f(x) \in \mathbb{F}_q$  of degree  $2d$ , there exists a polynomial  $g(x) \in \mathbb{F}_q$  s.t.  $f(x) | g(x)^p - g(x)$  and the degree of  $g(x)$  is at most  $2d - 1$ . We also saw that if we could find this  $g(x)$  efficiently then we could factor efficiently. We will proceed to show how to find  $g$  efficiently.

Recall also that the field  $\mathbb{F}_q$  is isomorphic to the  $t$ -dimensional (additive) vector space  $\mathbb{F}_p^t$ , where the isomorphism maps every element  $\alpha \in \mathbb{F}_q$  to a vector  $v_\alpha \in \mathbb{F}_p^t$ .

**Claim 1** *The map  $A : v_\alpha \mapsto v_{\alpha^p}$  is a linear map.*

### Proof

We only need to verify that:

1.  $A(v_{\alpha+\beta}) = v_{(\alpha+\beta)^p} = v_{\alpha^p + \beta^p \pmod{p}} = v_{\alpha^p} + v_{\beta^p} = A(v_\alpha) + A(v_\beta)$
2.  $A(v_{a \cdot \alpha}) = v_{(a \cdot \alpha)^p} = v_{a^p \cdot \alpha^p} = v_{a^p} + v_{\alpha^p} = v_{a^p} + A(v_\alpha)$

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Since  $A$  is a linear map, it can be represented by a  $t \times t$  matrix  $A \in \mathbb{F}_p^{t \times t}$

**Fact 2** *Given one of the “nice” representations of  $\mathbb{F}_q$  (e.g.  $\mathbb{F}_q$  represented as a vector space or using an irreducible polynomial), the matrix  $A$  can be computed efficiently.*

How does this fact help us? We want to find  $g(x)$  s.t.  $f(x) | g(x)^p - g(x)$ , where  $f(x)$  is known but  $g(x)$  is unknown. We will use the linear map  $A$  to find  $g(x)$ ! We view  $g(x)$  as  $g(x) = \sum_{i=0}^{2d-1} c_i \cdot x^i$ , where the  $c_i$ 's are unknowns, and get that:

$$g(x)^p = \left( \sum_{i=0}^{2d-1} c_i \cdot x^i \right)^p = \sum_{i=0}^{2d-1} c_i^p \cdot x^{i \cdot p}$$

To find  $g(x)$  we will construct a system of linear equations. Towards this end we define two new polynomials  $h(x), a(x)$  where  $h(x) = g(x)^p$  and  $a(x) \cdot f(x) = g(x)^p - g(x) = h(x) - g(x)$ .

Let  $\{e_i\}_{i=0}^{p \cdot (2d-1)}$  and  $\{a_i\}_{i=0}^{p \cdot (2d-1) - 2d}$  be the coefficients of  $h(x)$  and  $a(x)$  respectively. We get that:

$$h(x) = \sum_{j=0}^{p \cdot (2d-1)} e_j \cdot x^j = \sum_{i=0}^{2d-1} c_i^p \cdot x^{i \cdot p} = g(x)^p$$

1. The first system of constraints will reflect the equality  $h(x) = g(x)^p$ :
  - (a) For any integer  $j$  that is not a multiple of  $p$ :  $e_j = 0$ .
  - (b) For any integer  $i$ :  $e_{i \cdot p} = c_i^p = A \times c_i$ .
2. The second constraint specifies that  $f(x) \cdot a(x) = h(x) - g(x)$ . Looking at the coefficients on both sides and at  $f(x)$  as  $\sum_{i=0}^{2d} f_i \cdot x^i$ , for the  $j$ -th coefficient we get the constraint:

$$e_j - c_j = \sum_{i=0}^j f_i \cdot a_{j-i} = \sum_{i=0}^j M_{f_i} \cdot a_{j-i}$$

Where  $M_{f_i}$  is the matrix representation of  $f_i$  (recall this matrix representation supports multiplication).

3. Finally, we would like for the solution to be non-trivial, and thus we add the constraint  $(c_1, \dots, c_{2d-1}) \neq (0, \dots, 0)$ . Note that while this is not a linear equation per se, it can be incorporated into the algorithm for solving the other linear equations, so that the algorithm returns a non-zero solution when one exists.

Now, to find  $g(x)$  all that remains is to solve this system of (linear) equations! Note that this is *not* a proof of existence of a non-trivial  $g(x)$ , we proved  $g(x)$ 's existence in the previous lecture, this is simply an efficient procedure for finding  $g(x)$ .

## 2 Framework for the Next Talks

In the next talks we see how to factor bivariate polynomials and polynomials over the rational numbers  $\mathbb{Q}[x]$ . We begin by laying out the framework that we will follow in these (surprisingly) related results.

**Factoring Bivariate Polynomials** We will see how to go from factoring polynomials to factoring bivariate polynomials, we will go from factoring  $\mathbb{R}[x]$  to factoring  $\mathbb{R}[x, y]$ . Given  $f(x, y) \in \mathbb{R}[x, y]$ , we will factor it using an algorithm for factoring in  $\mathbb{R}[x]$ . We proceed in several steps:

1. Somehow (the details will follow) “perturb”  $f(x, y)$  into  $\tilde{f}(x, y)$ .
2. Begin by factoring  $\tilde{f}(x, y) \pmod{y}$  using the algorithm for factoring in  $\mathbb{R}[x]$ .
3. Proceed in Hensel iterations, and progressively go from factoring  $\tilde{f}(x, y) \pmod{y^i}$  to factoring  $\tilde{f}(x, y) \pmod{y^{2i}}$ .
4. From factoring over  $\mathbb{R}[x, y] \pmod{y^t}$ , go to factoring over  $\mathbb{R}[x, y]$ .

**Factoring over  $\mathbb{Q}[x]$ :** To factor polynomials over integers  $\mathbb{Z}[x]$ , we actually factor over  $\mathbb{Q}[x]$  (we couldn't really expect to factor over  $\mathbb{Z}[x]$ , since the polynomials of degree 0 there are integers...). We proceed similarly to the bivariate case:

1. Somehow pick a “nice” prime  $p$ .
2. Begin by factoring  $f(x) \pmod{p}$ .
3. Proceed in Hensel iterations, and progressively go from factoring  $f(x) \pmod{p^i}$  to factoring  $f(x) \pmod{p^{2i}}$ .
4. From factors over  $\mathbb{Z}[x] \pmod{p^t}$ , go to factoring over  $\mathbb{Z}[x]$ .

As can be seen, the two seemingly unrelated problems of factoring integers and bivariate polynomials, are actually closely tied together by our plan of action and its use of Hensel iterations.

### 3 Hensel's Lifting Lemma

We want to go from a factorization  $f(x) = g(x) \cdot h(x) \pmod{p}$  to  $f(x) = \tilde{g}(x) \cdot \tilde{h}(x) \pmod{p^2}$ . One appealing idea is to take  $\tilde{g}(x) = g(x) \pmod{p}$  and  $\tilde{h}(x) = h(x) \pmod{p}$ . Unfortunately, this natural idea fails, as can be seen in the simple case:

$$f(x) = x^2 - 2x + 6 = (x - 1) \cdot (x - 1) \pmod{5}$$

We want  $\tilde{g}(x) = (x - 1) + 5 \cdot a(x)$  and  $\tilde{h}(x) = (x - 1) + 5 \cdot b(x)$ , which implies that modulo 25 we should get:  $f(x) = (x - 1)^2 + 5 \cdot (x - 1) \cdot (a(x) + b(x)) + 25a(x) \cdot b(x)$ . Unfortunately,  $f(x)$  isn't of this form modulo 25!

To overcome this obstacle, we observe that our natural idea may have failed in the example above simply because the factors  $g(x), h(x)$  were not relatively prime. Before stating the Lemma itself, note that by  $J^2$  we refer to the collection of linear combinations of products of pairs of items in  $J$ .

**Lemma 3** *Hensel's Lifting Lemma:*

*For a ring  $R$  and an ideal  $J \subseteq R$ :*

**If** *there exist  $f, g, h, a, b \in R$  such that:*

1.  $f - g \cdot h \in J$  ( $f = g \cdot h \pmod{J}$ ).
2.  $a \cdot g + b \cdot h = 1 \pmod{J}$  ( $f$  and  $g$  are relatively prime).

**Then** *there exists a lifting: there exist  $\tilde{g}, \tilde{h} \in R$  such that:*

1.  $\tilde{g} = g \pmod{J}$ .
2.  $\tilde{h} = h \pmod{J}$ .
3.  $f = \tilde{g} \cdot \tilde{h} \pmod{J^2}$ .

We refer to the set of conditions satisfied by  $\tilde{g}$  and  $\tilde{h}$  as  $(*)$ .

The lift is **unique**: for any  $g^*, h^*$  satisfying  $(*)$ , there exists  $u \in J$ , such that  $g^* = \tilde{g} \cdot (1+u)$  and  $h^* = \tilde{h} \cdot (1-u)$ .

Furthermore, for any  $\tilde{g}, \tilde{h}$  that satisfy  $(*)$ , there exist  $\tilde{a}, \tilde{b} \in R$ , such that  $\tilde{a} \cdot \tilde{g} + \tilde{b} \cdot \tilde{h} = 1 \pmod{J^2}$ . Thus the new factors are also relatively prime and we can continue to activate Hensel's Lemma.

### Proof

We prove each of the guaranteed properties separately:

**The existence of a lifting:** We proceed as before (but with relatively prime factors!).

$f = g \cdot h + q$  for some  $q \in J$ ,  $\tilde{g} = g + g_1$ ,  $\tilde{h} = h + h_1$ , where  $g_1, h_1 \in J$ .

We get that:  $\tilde{g} \cdot \tilde{h} = g \cdot h + g_1 \cdot h + h_1 \cdot g + h_1 \cdot g_1$ .

Since  $h_1 \cdot g_1 \in J^2$ , it remains to show that  $q = g_1 \cdot h + h_1 \cdot g + h_1$ .

We still haven't specified  $g_1, h_1$ , so to satisfy this condition we take  $g_1 = b \cdot q$ ,  $h_1 = a \cdot q$ , and get that  $g_1 \cdot h + h_1 \cdot g + h_1 = q \cdot (b \cdot h + a \cdot g) = q$ , as required!

**$\tilde{g}$  and  $\tilde{h}$  are relatively prime:** Observe that:  $a \cdot \tilde{g} + b \cdot \tilde{h} = a \cdot g + b \cdot h + r' = 1 + r$ , for some  $r', r \in J$ . Now we can take  $\tilde{a} = a \cdot (1-r)$  and  $\tilde{b} = b \cdot (1-r)$ , and get that:

$$\tilde{a} \cdot \tilde{g} + \tilde{b} \cdot \tilde{h} = (1-r) \cdot (a \cdot \tilde{g} + b \cdot \tilde{h}) = (1-r)(1+r) = 1 - r^2 = 1 \pmod{J^2}$$

**Uniqueness:** Let  $g^* = \tilde{g} + g_2$  and  $h^* = \tilde{h} + h_2$  for some  $g_2, h_2 \in J$  (because, modulo  $J$ , we know that  $g^* = g = \tilde{g}$  and  $h^* = h = \tilde{h}$ ). Furthermore, modulo  $J^2$ , we know that  $g^* \cdot h^* = f = \tilde{g} \cdot \tilde{h}$ .

Now we get that:  $g^* \cdot h^* = \tilde{g} \cdot \tilde{h} + g_2 \cdot \tilde{h} + h_2 \cdot \tilde{g} + g_2 \cdot h_2$ . This implies that  $g_2 \cdot \tilde{h} + h_2 \cdot \tilde{g} \in J^2$  (because  $g_2 \cdot h_2 \in J^2$  and  $g^* \cdot h^* = \tilde{g} \cdot \tilde{h} \pmod{J^2}$ ).

**Claim 4** *The only way to get that  $g_2 \cdot \tilde{h} + h_2 \cdot \tilde{g} \in J^2$  is by setting  $g_2 = u \cdot \tilde{g}$  and  $h_2 = -u \cdot \tilde{h}$  for some  $u \in J$ .*

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Note that in class it was pointed out that these are existence results. We did not reach a definitive conclusion about whether there is a problem in actually finding  $r, q$  etc.

In the next talk we will complete the procedure for factorizing bivariate polynomials.