



DS-210: PROGRAMMING FOR DATA SCIENCE

LECTURE 36

1. BINARY SEARCH

2. GREEDY ALGORITHMS

3. DIVIDE AND CONQUER





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BINARY SEARCH

Input: sorted array/vector v

Task: find if a specific element x appears in it





BINARY SEARCH

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Task: find if a specific element x appears in it

General strategy:

- maintain range $left..right$ within v of where x could be
- repeat:
 - ask about the middle of the range
 - if x found, celebrate
 - if the middle element $< x$, narrow search to the right half
 - otherwise, narrow search to the left half





LET'S IMPLEMENT IT!





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Might be harder than you think!

Jon Bentley in "Programming pearls" claims that only 10% programmers succeed, even given unlimited amount of time





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Ad:

- Great book if you are interested in programming and basic algorithms
- I only know the first edition (mostly uses pseudocode)
- 2nd edition focused on C++ (probably still great)
- very cheap on eBay!





LET'S IMPLEMENT IT!

```
In [2]: fn present(mut data:&[i32], element:i32) -> bool {
    let (mut left, mut right) = (0, data.len());
    // invariant: if element has not been found, it must be in data[left..right]
    while left < right {
        let middle = (left+right)/2;
        if data[middle] == element {
            return true
        } else if data[middle] > element {
            right = middle
        } else {
            left = middle + 1
        }
    }
    false
}
```




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```
In [3]: let v = vec![-16, -4, 0, 2, 4, 12, 32, 48, 48, 111];
```

```
In [4]: present(&v, -16)
```

```
Out[4]: true
```

```
In [ ]: present(&v, 5)
```

```
In [ ]: present(&v, 1000)
```

```
In [ ]: present(&v, 32)
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In [ ]: present(&v, 1000)
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```
In [5]: present(&v, 5)
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```
Out[5]: false
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In [ ]: present(&v, 32)
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In [4]: present(&v, -16)
```

```
Out[4]: true
```

```
In [6]: present(&v, 1000)
```

```
Out[6]: false
```

```
In [5]: present(&v, 5)
```

```
Out[5]: false
```

```
In [ ]: present(&v, 32)
```





LET'S IMPLEMENT IT!

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In [4]: present(&v, -16)
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```
Out[4]: true
```

```
In [6]: present(&v, 1000)
```

```
Out[6]: false
```

```
In [5]: present(&v, 5)
```

```
Out[5]: false
```

```
In [7]: present(&v, 32)
```

```
Out[7]: true
```





1. BINARY SEARCH

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GREEDY ALGORITHMS

- Make locally best (or any) decision towards solving a problem





EXAMPLES WE SAW

- Heuristics for creating decision trees
 - select "best" single split and recurse
- Shortest paths (Dijkstra's algorithm)
 - select the vertex known to be closest
 - try routing paths through it
 - **Gives globally optimal solution!!!**





ADDITIONAL EXAMPLES

- Minimum spanning tree: find cheapest overall subset of edges so that the graph is connected
 - Kruskal's algorithm: keep adding the cheapest edge that connects disconnected groups of vertices





ADDITIONAL EXAMPLES

- Minimum spanning tree: find cheapest overall subset of edges so that the graph is connected
 - Kruskal's algorithm: keep adding the cheapest edge that connects disconnected groups of vertices
- Matching: matching conference attendees to available desserts they like
 - Another formulation: maximum size set of independent edges in graph
 - Keep adding edges as long as you can
 - This will give factor 2 approximation





1. BINARY SEARCH IN A SORTED VECTOR

2. GREEDY ALGORITHMS

3. DIVIDE AND CONQUER





DIVIDE AND CONQUER

If your problem is too difficult:

- partition it into subproblems
- solve the subproblems
- combine their solutions into a solution to the entire problem





DIVIDE AND CONQUER

If your problem is too difficult:

- partition it into subproblems
- solve the subproblems
- combine their solutions into a solution to the entire problem

Our plan: see two classic divide and conquer sorting algorithms

How would you do this?





MERGE SORT

Recursively:

- sort the first half
- sort the second half
- merge the results





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Complexity for n elements?





MERGE SORT

Recursively:

- sort the first half
- sort the second half
- merge the results

Complexity for n elements?

- Merging two lists of Q and R elements takes $O(R + Q)$ time
- $O(\log n)$ levels of recursion: $O(n)$ work on each level
- $O(n \log n)$ time overall





IMPLEMENTING MERGING

```
In [8]: fn merge(v1:Vec<i32>, v2:Vec<i32>) -> Vec<i32> {
    let (l1,l2) = (v1.len(), v2.len());
    let mut merged = Vec::with_capacity(l1+l2);
    let (mut i1, mut i2) = (0,0);
    while i1 < l1 {
        if (i2 == l2) || (v1[i1] <= v2[i2]) {
            merged.push(v1[i1]);
            i1 += 1;
        } else {
            merged.push(v2[i2]);
            i2 += 1;
        }
    }
    while i2 < l2 {
        merged.push(v2[i2]);
        i2 += 1;
    }
    merged
}
```





IMPLEMENTING MERGING

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In [8]: fn merge(v1:Vec<i32>, v2:Vec<i32>) -> Vec<i32> {
  let (l1,l2) = (v1.len(), v2.len());
  let mut merged = Vec::with_capacity(l1+l2);
  let (mut i1, mut i2) = (0,0);
  while i1 < l1 {
    if (i2 == l2) || (v1[i1] <= v2[i2]) {
      merged.push(v1[i1]);
      i1 += 1;
    } else {
      merged.push(v2[i2]);
      i2 += 1;
    }
  }
  while i2 < l2 {
    merged.push(v2[i2]);
    i2 += 1;
  }
  merged
}
```

```
In [9]: let v1 = vec![3,4,8,11,12];
let v2 = vec![1,2,3,9,22];
merge(v1,v2)
```

```
Out[9]: [1, 2, 3, 3, 4, 8, 9, 11, 12, 22]
```





IMPLEMENTING MERGE SORT

```
In [10]: fn merge_sort(input:&[i32]) -> Vec<i32> {  
    if input.len() <= 1 {  
        input.to_vec()  
    } else {  
        let split = input.len() / 2;  
        let v1 = merge_sort(&input[..split]);  
        let v2 = merge_sort(&input[split..]);  
        merge(v1,v2)  
    }  
}
```

```
In [11]: let v = vec![2,4,21,6,2,32,62,0,-2,8];  
merge_sort(&v)
```

```
Out[11]: [-2, 0, 2, 2, 4, 6, 8, 21, 32, 62]
```





QUICK SORT

- Select an arbitrary (random?) element x
- Partition your vector:
 - Move elements lower than x to the left
 - Move elements greater than x to the right
- Sort the left part and right part





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QUICK SORT

- Select an arbitrary (random?) element x
- Partition your vector:
 - Move elements lower than x to the left
 - Move elements greater than x to the right
- Sort the left part and right part

Complexity for n elements?

- Partitioning k elements takes $O(k)$ time
- Intuition: The size of the problem usually decreases by constant factor in a recursive call
- Expected time: $O(n \log n)$ time overall





IMPLEMENTING PARTITIONING

```
In [12]: fn partition(input:&mut [i32], pivot: i32) -> (usize,usize) {
    // move numbers lower than pivot to the left
    let mut left = 0;
    for i in 0..input.len() {
        if input[i] < pivot {
            input.swap(i,left);
            left += 1;
        }
    }
    // input[..left]: numbers lower than pivot

    // move numbers greater than pivot to the right
    let mut right = input.len();
    for i in (left..input.len()).rev() {
        if input[i] > pivot {
            right -= 1;
            input.swap(i,right);
        }
    }
    // input[right..]: numbers greater than pivot

    (left,right)
}
```





IMPLEMENTING QUICKSORT

```
In [13]: :dep rand
use rand::Rng;

fn quicksort(input:&mut [i32]) {
    if input.len() >= 2 {
        // pivot = random element from the input
        let pivot = input[rand::thread_rng().gen_range(0..input.len())];

        let (left,right) = partition(input,pivot);

        quicksort(&mut input[..left]);
        quicksort(&mut input[right..]);
    }
}
```

```
In [14]: let mut v = vec![145,12,3,7,83,12,8,64];
quicksort(&mut v);
v
```

```
Out[14]: [3, 7, 8, 12, 12, 64, 83, 145]
```

