



DS-210: PROGRAMMING FOR DATA SCIENCE

LECTURE 34

1. BINARY SEARCH TREES

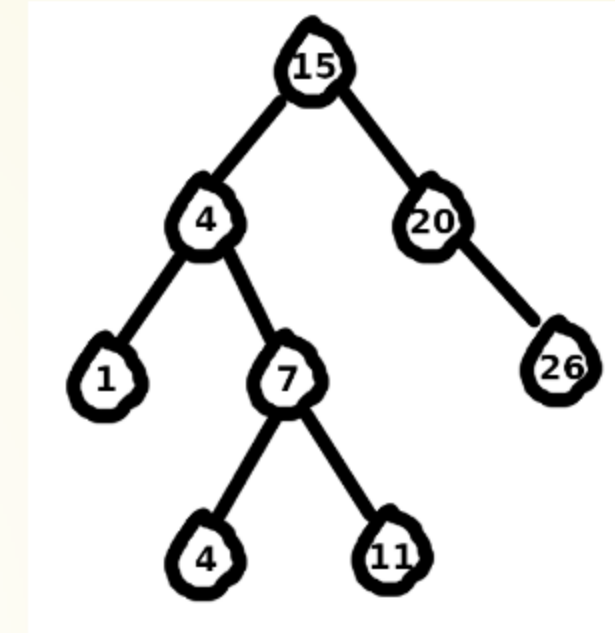
2. APPLICATIONS (RANGE SEARCHING)

3. RUST: BTreeMap AND BTreeSet



BINARY SEARCH TREES

- Organize data into a binary tree
 - Similar to binary heaps

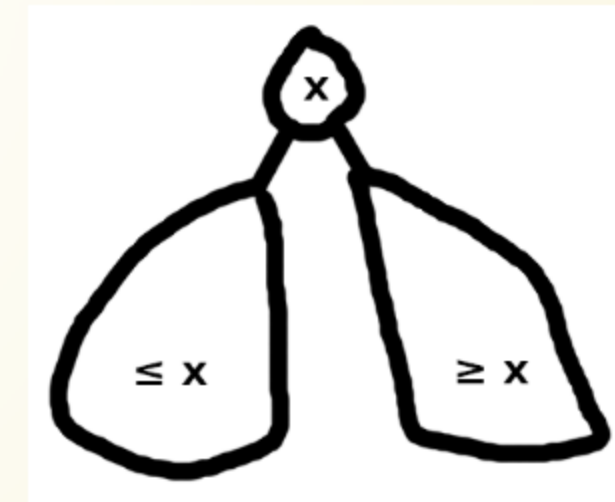
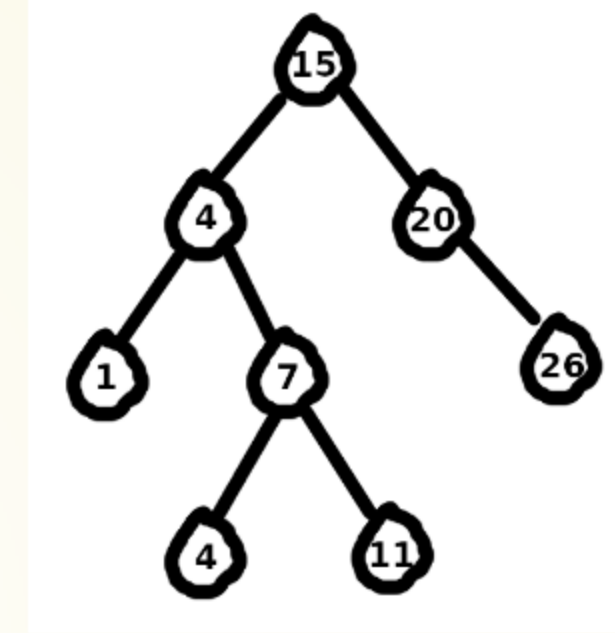




BINARY SEARCH TREES

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 - Similar to binary heaps

- Invariant at each node:
 - all left descendants \leq parent
 - parent \leq all right descendants



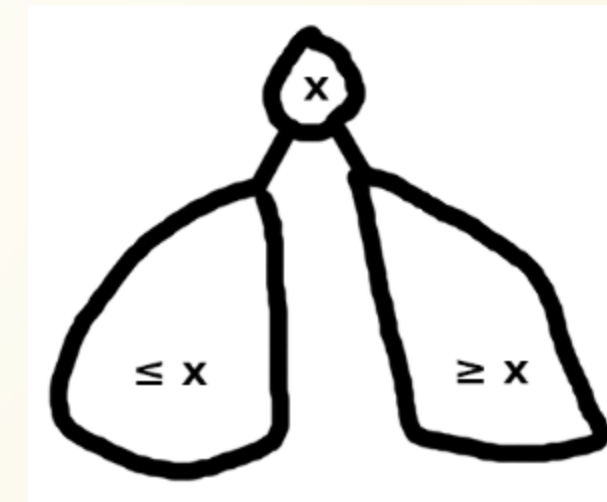
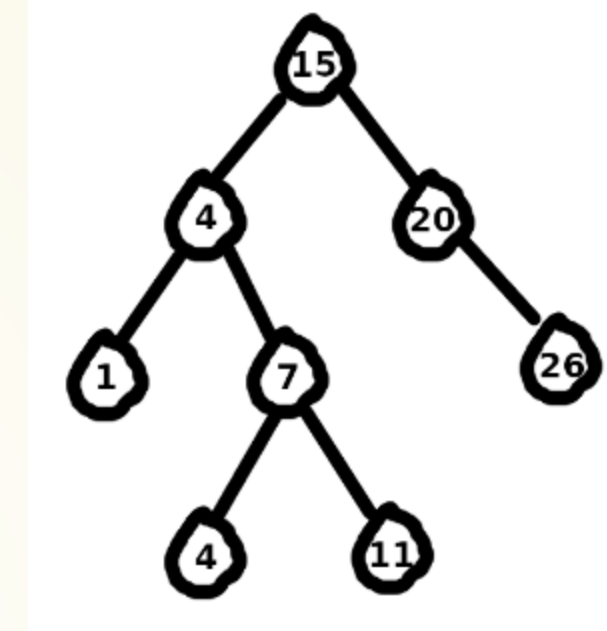


BINARY SEARCH TREES

- Organize data into a binary tree
 - Similar to binary heaps

- Invariant at each node:
 - all left descendants \leq parent
 - parent \leq all right descendants

- Compared to binary heaps:
 - different ordering of elements





BASIC OPERATIONS: FIND A KEY k

How can we do this?





BASIC OPERATIONS: FIND A KEY k

How can we do this?

- Descend recursively from the root until k found or stuck:
 - If $k <$ value at the current node, go left
 - If $k >$ value at the current node, go right

[see examples on the board]





BASIC OPERATIONS: INSERT A KEY k

How can we do this?





BASIC OPERATIONS: INSERT A KEY k

How can we do this?

- Keep descending from the root until you leave the tree
 - If $k \leq$ value at the current node, go left
 - If $k >$ value at the current node, go right
- Create a new node containing k there

[see examples on the board]





BASIC OPERATIONS: DELETE A NODE

How can we do this?





BASIC OPERATIONS: DELETE A NODE

How can we do this?

- More complicated: need to find a replacement
- If the node is a leaf: nothing to do
- If only one child: move the child up
- Otherwise:
 - find the **rightmost** descendant in the **left** subtree
 - it will have at most one child

[see examples on the board]





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Bad news: the depth can be made proportional to n , the number of nodes

Good news: smart ways to make the depth $O(\log n)$





BALANCED BINARY SEARCH TREES

There are smart ways to rebalance the tree!

- Depth: $O(\log n)$
- Usually additional information has to be kept at each node
- Popular examples:
 - Red-black trees
 - AVL trees
 - ...





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REASON 1:

- Good worst case behavior: no need for a good hash function

REASON 2:

- Can answer efficiently questions such as:
 - What is the smallest/greatest element?
 - What is the smallest element greater than x ?
 - List all elements between x and y





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- Like above, ignoring whole subtrees smaller than x
- Will get the first element greater than x in $O(\log n)$ time





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For balanced trees: listing t first greater elements takes $O(t + \log n)$ time



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- Not exactly
- For efficiency reasons, *B*-trees:
 - generalization of binary trees
 - between *B* and $2B$ keys in a node
 - corresponding number of subtrees





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Where can you meet *B*-trees

- Traditionally, very popular in databases
- Interesting that now considered more efficient for in memory operations





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Sets and maps, respectively





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use std::collections::BTreeSet;
let mut set: BTreeSet<i32> = BTreeSet::new();
set.insert(5);
set.insert(7);
set.insert(11);
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set.range(7..24).for_each(|x| println!("{}", x));
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```
In [4]: // listing a range: another way of specifying it
use std::ops::Bound::{Included, Excluded};
set.range((Excluded(5), Included(11))).for_each(|x| println!("{}", x));
```

```
7
11
```